## **DeviceNET®**

Ranges: 0-45° to 0-200 Turns

# **Industrial Grade**

# **Specification Summary:**

#### **GENERAL**

Full Stroke Ranges	0-0.125 to 0-200 turns
Electrial Interface	CANbus ISO 11898
Protocol	DeviceNet Version 2.0
Accuracy	see ordering information
Repeatability	± 0.02% full stroke
Resolution	± 0.003% full stroke
Enclosure Material powder-p	painted aluminum or stainless steel
Sensor plas	tic-hybrid precision potentiometer
Shaft Loading	. up to 10 lbs. radial and 5 lbs. axial
Starting Torque (25°C)	2.0 in-oz., max
Weight, Aluminum (Stainless Steel) Enclosure	3 lbs. (6 lbs.), max.

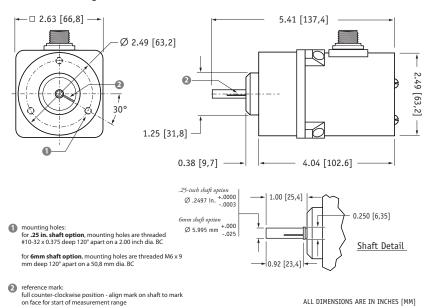
#### **ELECTRICAL**

Input Voltage			Bus Powere	d
Input Current			40 m	Α
Address Setting (	Node ID)	063 set via DIF	Switches—default setting: 6	3
Baud Rate			or 500K set via DIP Switche	S
EDS file		available @ http://v	www.celesco.com/downloa	d

#### **ENVIRONMENTAL**

Enviromental Suitability	NEMA 4/4X/6, IP67/68
Operating Temperature	40° to 200°F
Vibration	. up to 10 G's to 2000 Hz maximum

### Outline Drawing



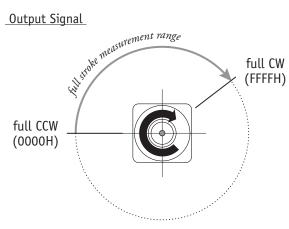
# RT8DN

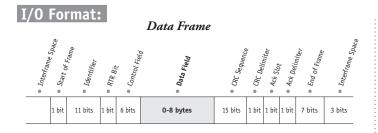


Celesco's model RT8DN communicates rotational position feedback via DeviceNET® to your programmable controller. The heart of this sensor is a precision plastic-hybrid position potentiometer which provides a "absolute" position and does not ever have to be reset to a "home" position after a power loss or planned shutdown.

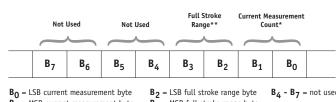
This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/8 to 200 turns.

Output Signal





#### Data Field



**B**<sub>1</sub> = MSB current measurement byte

**B**<sub>3</sub> = MSB full stroke range byte

 $B_4 - B_7 = \text{not used}$ 

#### \*Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies the first two bytes ( $B_0$  and  $B_1$ ) of the data field.  $B_0$  is the LSB (least significant byte) and B<sub>1</sub> is the MSB (most significant byte).

The CMC starts at 0000H with shaft at the full counter-clockwise position (0° reference mark) and continues in the clockwise direction to the end of the stroke range stopping at FFFFH. This holds true for all ranges.

#### \*\*Full Stroke Range

The Full Stroke Range (FSR) is a 16-bit value in the data field that expresses the full range of the sensor in degrees. This value can be used to convert the actual count to units of measurement should the application require it.

The full stroke measurement range occupies the second two bytes (B2 and B3) of the data field.

B2 is the LSB (least significant byte) and B3 is the MSB (most significant byte).

This value is expressed in degrees.

#### Example:

Hex Value	Decimal Equivalent	Full Stroke Range
0168	360	360 degrees

#### Converting CMC to Degrees

If required, the CMC can easily be converted to a rotational measurement expressed in degrees instead

This is accomplished by first dividing the CMC by 65,535 (total counts over the range) and then multiplying that value by the FSR:

$$\left(\begin{array}{c} \text{CMC} \\ \hline 65,535 \end{array}\right)$$
 X FSR

#### Example:

If the full stroke range is 1 turn (360 degrees) and the current position is OFF2 Hex (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 360 deg. = 22.4 degrees

#### Address Setting (Node ID), Baud Rate and Bus Termination Settings

#### Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number  $1 (= 2^0)$  and ending with switch number  $6 (= 2^5)$ .

<b>DIP-1</b> (2 <sup>0</sup> )	<b>DIP-2</b> (2 <sup>1</sup> )	<b>DIP-3</b> (2 <sup>2</sup> )	<b>DIP-4</b> (2 <sup>3</sup> )	<b>DIP-5</b> (2 <sup>4</sup> )	<b>DIP-6</b> (2 <sup>5</sup> )	address (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
•••	•••	•••	•••	•••	•••	•••
1	1	1	1	1	1	63

## **Baud Rate**

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

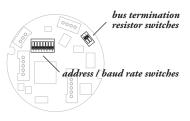
DIP-7	DIP-8	baud rate								
0	0	125k								
1	0	250k								
0	1	500k								
1	1	125k								

#### **Bus Termination**

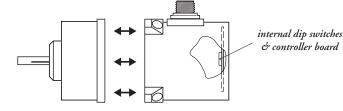
The setting of the internal bus termination resistor may be specified upon order or manually changed by the end user at the time of installation.

The bus termination resistor is activated setting switches 1 & 2 on the 2-pole DIP switch (located on the internal DeviceNET controller board) to the "ON" position.

#### **DeviceNET Controller Board and DIP Switch Location**



to gain access to the controller board, remove four Allen-Head Screws and separate case halves



## Ordering Information:

## Model Number:

Sample Model Number:

RT8DN - 100 - AL - 25 - FL - 500 - TR - SC5

R range: A enclosure:
B shaft:

100 turns powder-painted aluminum

mounting style:

.25-in diameter flange

baud rate:
terminating resistor:

500 k bits/sec.

**6** electrical termination:

5-meter cordset with straight plug

Full Stroke Range:

<b>R</b> order code:	R125		R25		R50		1		2		3		5		10		20
clockwise shaft rotations, min:	0.125	:	0.25	:	0.50	:	1	:	2	:	3	:	5	:	10	:	20
accuracy (% of f.s.):	1.25%	:	1.25%	:	0.5%	:	0.5%	:	0.5%	:	0.2%	:	0.2%	:	0.15%	:	0.15%
potentiometer cycle life*:	2.5 x 106		2.5 x 106	:	2.5 x 106		2.5 x 10 <sup>6</sup>		2.5 x 106		5 x 10 <sup>5</sup>		5 x 10 <sup>5</sup>		$2.5 \times 10^{5}$		$2.5 \times 10^{5}$

<b>R</b> order code:	30		40		50	80		100		120		140		180		200
clockwise shaft rotations, min:	30	:	40	:	50	80	:	100	:	120	:	140	:	180	:	200
accuracy (% of f.s.):	0.15%	:	0.15%	:	0.15%	0.15%	:	0.15%	:	0.15%	:	0.15%	:	0.15%	:	0.15%
potentiometer cycle life*:	2.5 x 10 <sup>5</sup>	:	$2.5 \times 10^5$	:	2.5 x 10 <sup>5</sup>	2.5 x 10 <sup>5</sup>		2.5 x 10 <sup>5</sup>	: 2	2.5 x 10 <sup>5</sup>	:	$2.5 \times 10^5$	:	$2.5 \times 10^5$	:	$2.5 \times 10^5$

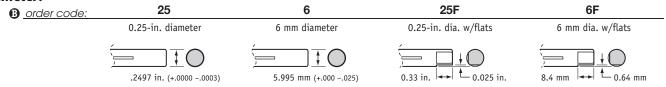
<sup>\*–</sup>number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

## **Enclosure Material:**

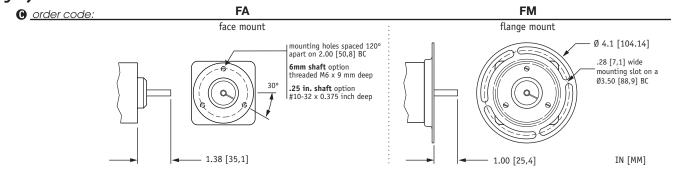
SS ♠ order code:

303 stainless steel powder-painted aluminum

## **Shaft Diameter:**



# **Mounting Style:**



## **RT8DN** • **Rotational Transducer: DeviceNET**®

## Ordering Information:

## **Baud Rate:**

**125 250 500**125 kbaud 250 kbaud 500 kbaud

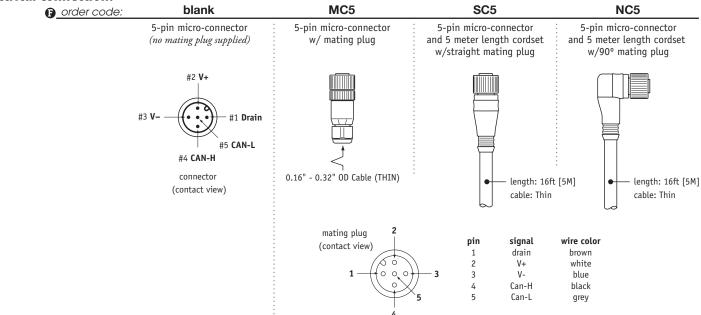
# **Terminating Resistor:**

• order code: TR NR

terminating resistor

no terminating resistor

## **Electrical Connection:**



version: 5.0 last updated: July 20, 2010

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